A METHOD FOR THE EFFICIENT MODELLING OF DELAMINATION IN LARGE STRUCTURES

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Introduction

n Need for the modelling of delamination **in large structures**, an example:



Headform impact (pedestrian safety):

Energy: 212 Joules Mass: 4.5 kg Velocity: 9.7 ms⁻¹ Diameter: 165 mm

About **50 positions** to model on the hood.

Simulation time (26cpus):

Steel hood: Composite hood:

22 minutes 8 hours **x 22**









Introduction

n Need for the modelling of delamination **in large structures**, an example:



VERSITY OF TECHNOLOGY

Delamination modelling (State of the art)



Present modelling strategy











Present modelling strategy





Composite Structures (2020) Främby (2020), Eng. Fract. Mech.









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Stress Recovery Basics

□ Linear Shell elements (ESL based on FSDT) present:



Stress Recovery Basics

■ Linear Shell elements (ESL based on FSDT) present:

Several authors have proposed using the stress equilibrium equations :

$$\sigma_{11,1} + \sigma_{12,2} + \sigma_{13,3} = 0$$

$$\sigma_{13,1} + \sigma_{23,2} + \sigma_{33,3} = 0$$

$$\sigma_{13} = -\int_{-\frac{h}{2}}^{z} \sigma_{11,1} + \sigma_{12,2} dz + C_{1}$$

$$\sigma_{33} = \iint_{-\frac{h}{2}}^{z} \sigma_{11,11} + \sigma_{22,22} + 2\sigma_{12,12} dz dz + C_{3}$$

These equations have been generalized for arbitrarily curved geometries.

An efficient formulation, based on the shell forces and moments is used.

 σ_{13} , σ_{23} and σ_{33} are recovered in a post-processing step.











D Laminate:

 $[(0; 90; 45; -45)_2; -45; 45; 90; 0; -45; 45; 0_8; 90; 0]$

- ≻ Layer thickness : 0.25 mm
- ➤ Total thickness : 6 mm

D Prototype material:

E_{11}	$E_{22} = E_{33}$	$G_{12} = G_{13}$
100 GPa	10 GPa	5 GPa
G ₂₃	$v_{12} = v_{13} = v_{23}$	
4 GPa	0.25	









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Doubly-curved example: Bending



FOR STRUCTURAL DESIGN

































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Shell













Composite Part A (2023)









VCCT criterion

An initial crack is present: will it propagate?

□ The Energy Release Rate (ERR) is computed:

- $G_I = \frac{1}{2A^i} F_I^i \langle \Delta_I^{i-1} \rangle \quad ; \quad G_{II} = \frac{1}{2A^i} F_{II}^i \Delta_{II}^{i-1}.$
- $G_T = G_I + G_{II}.$
 - if $G_T > G_C$ (Benzeggagh-Kenane)

The fied at node *i* is released.

McElroy(2016). NASA/TP-2016-219211.



- Base node
- Extra node
- Coincident tied node pair
- Area A^i to be opened









VCCT criterion

■ An initial crack is present: will it propagate?



Cohesive law

□ When the VCCT criterion is met the force at the interface decreases:



The damage variable D ensures that the energy G_cA is dissipated









Validation: DCB, ENF, MMB

Benchmark dimension and material from:

Krueger (2015), J. Compos. Mater.

□ Material Fracture Process Zone ≈ 0.80 mm

Element length: 4 mm











Validation: DCB, ENF, MMB





















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Crack propagation

Case from: De Carvalho (2022), NASA/TM-20220002081



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Case	u_{top}	u_{bot}	Edges
Mode I	positive	négative	free
Mode II	negative	-	clamped









Case from: De Carvalho (2022), NASA/TM-20220002081



Case	u_{top}	u _{bot}	Edges
Mode I	positive	négative	free
Mode II	negative	-	clamped









Mode I

u_{top} = 0.1 mm



















Conclusions

Stress Recovery (Delamination initiation)

Accurate out-of-plane stresses can be obtained with ESL linear shells.
The model can be refined where there is a risk of delamination.
Can also be used as a post-processing tool.

VCCT-Cohesive approach (Delamination propagation)
The method is able to model crack propagation in large elements.
Does not introduce artificial stiffness.

Using these two methods,

delaminations can be modelled in large structures !









Project outlook ACCIÓ grant (INNOTEC)

Collaboration Btech – AMADE

■ End of project: July 2024

Collaboration with Chalmers continues in the frame of the thesis.











Thank you!

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