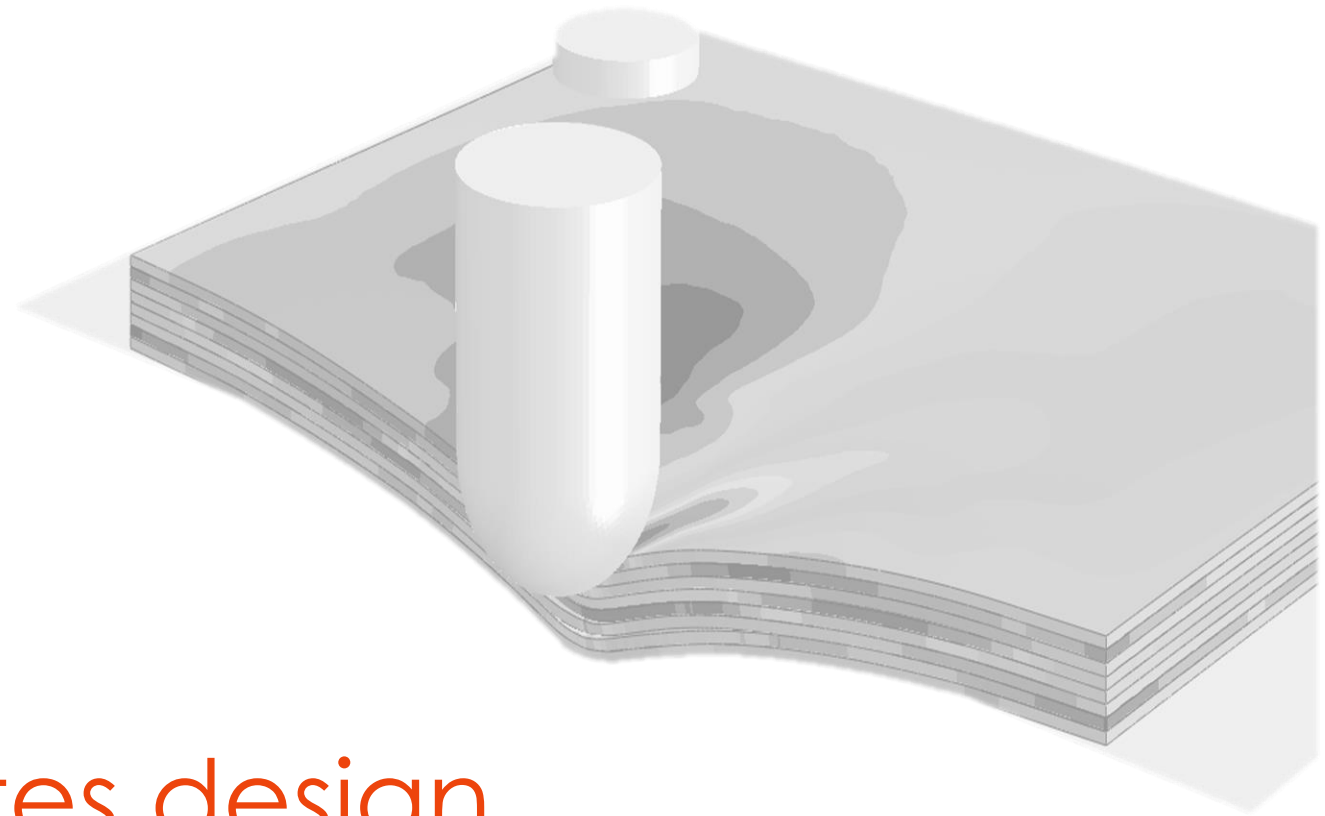


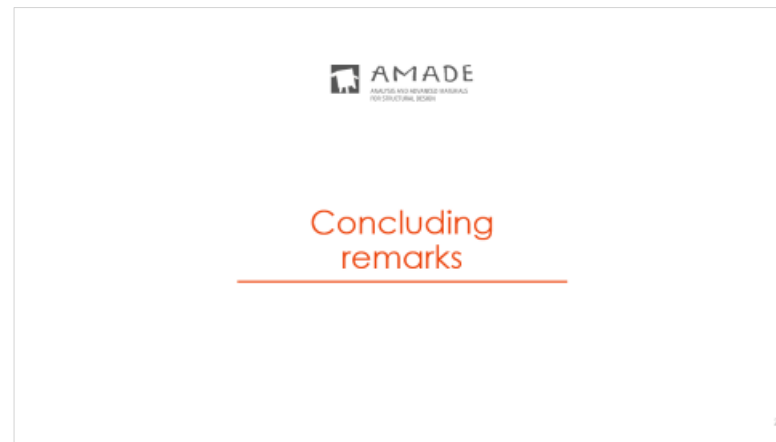
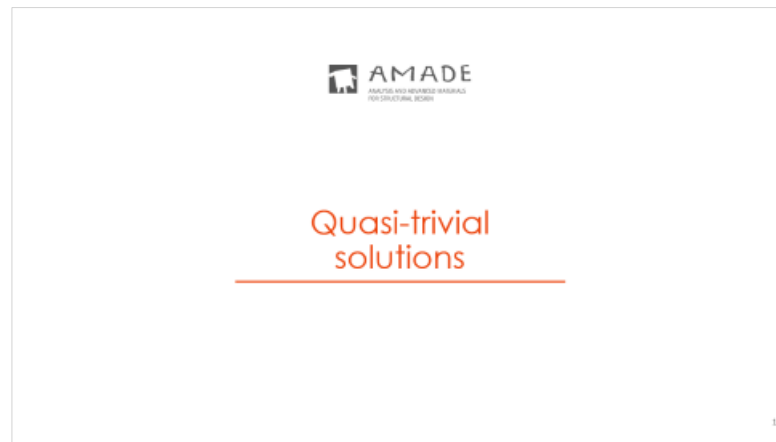
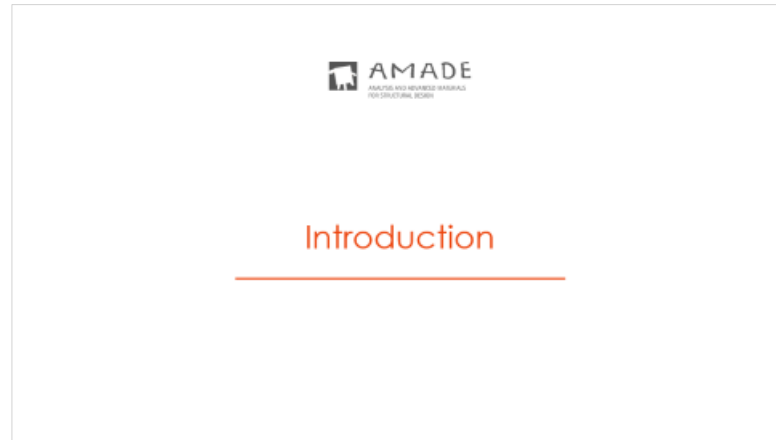
Quasi-Trivial solutions for composite laminates design



T. Garulli
Summer AMADE Day, Girona, 14th July 2023



Quasi-Trivial solutions for laminates design: contents





AMADE

ANALYSIS AND ADVANCED MATERIALS
FOR STRUCTURAL DESIGN

Introduction

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Do you know what a quasi-trivial solution is?

① Start presenting to display the poll results on this slide.



Do you know what a quasi-trivial solution is?

Multiple Choice Poll 36 votes 36 participants

No - 26 votes



Maybe... - 8 votes



Of course I do! - 2 votes



Quasi-Trivial (QT) solutions: discovery & definition



Composites Science and Technology 61 (2001) 1465–1473

COMPOSITES
SCIENCE AND
TECHNOLOGY

www.elsevier.com/locate/compscitech

A special class of uncoupled and quasi-homogeneous laminates

P. Vannucci*, G. Verchery

*LRMA, Laboratoire de Recherche en Mécanique et Acoustique, I.S.A.T., Institut Supérieur de l'Automobile et des Transports,
Université de Bourgogne, 49, Rue Mademoiselle Bourgeois, BP 31, 58027 Nevers Cedex, France*

Received 3 July 2000; received in revised form 20 February 2001; accepted 13 March 2001

Discovered in 2001 by
Vannucci and Verchery

“[...] **a particular class of solutions** for the two inverse problems of **finding uncoupled or quasi-homogeneous laminates** made by identical anisotropic layers. These solutions, called **quasi-trivial** [...]”

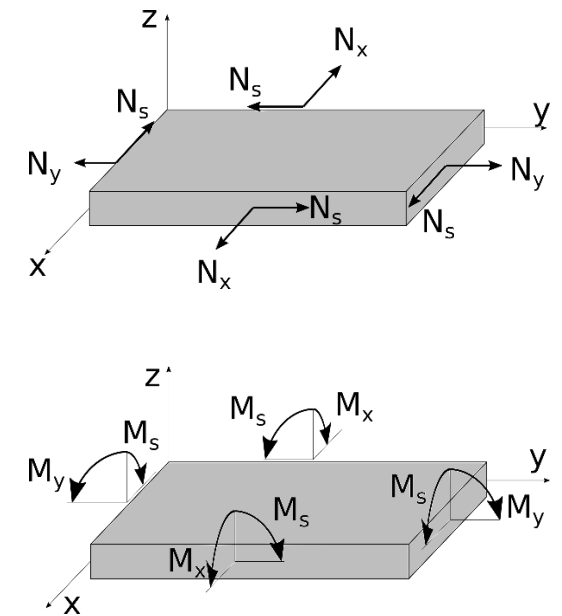




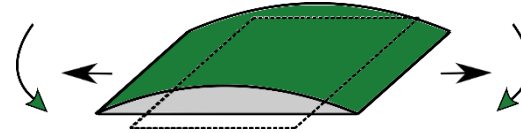
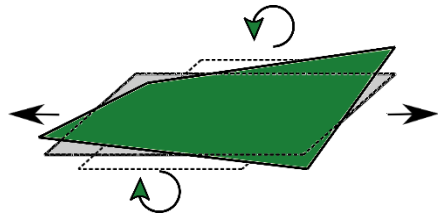
Elastic design of laminates

Laminate constitutive behavior (CLPT)

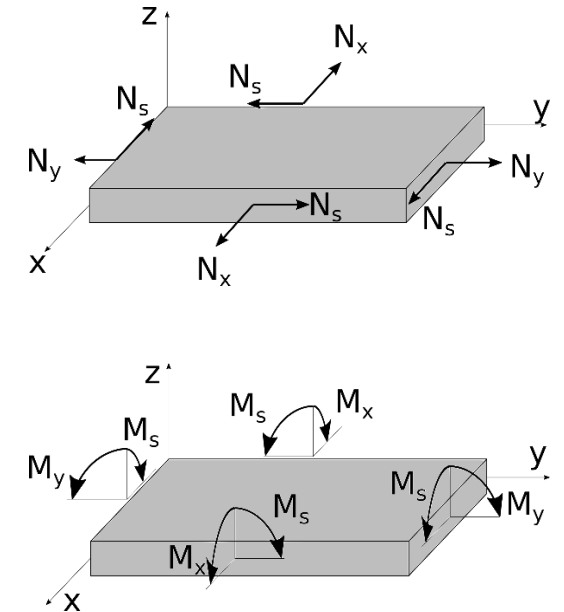
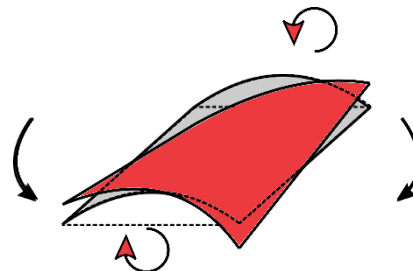
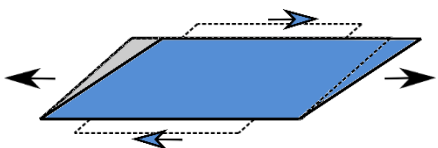
$$\begin{matrix}
 \text{In-plane force} \\
 \text{resultants} \\
 \left. \begin{matrix} N_x \\ N_y \\ N_s \end{matrix} \right\} \\
 \left. \begin{matrix} M_x \\ M_y \\ M_s \end{matrix} \right\} \\
 \text{Moments}
 \end{matrix}
 =
 \begin{matrix}
 \text{Extensional} \\
 \text{stiffness} \\
 \text{matrix} \\
 \begin{matrix} A_{11} & A_{12} & A_{16} \\ A_{12} & A_{22} & A_{26} \\ A_{16} & A_{26} & A_{66} \end{matrix} \\
 \text{Bending-} \\
 \text{extension} \\
 \text{coupling} \\
 \begin{matrix} B_{11} & B_{12} & B_{16} \\ B_{12} & B_{22} & B_{26} \\ B_{16} & B_{26} & B_{66} \end{matrix} \\
 \text{Bending} \\
 \text{stiffness} \\
 \text{matrix} \\
 \begin{matrix} D_{11} & D_{12} & D_{16} \\ D_{12} & D_{22} & D_{26} \\ D_{16} & D_{26} & D_{66} \end{matrix}
 \end{matrix}
 \begin{matrix}
 \text{Mid-plane} \\
 \text{strains} \\
 \left. \begin{matrix} \epsilon_x^0 \\ \epsilon_y^0 \\ \epsilon_s^0 \end{matrix} \right\} \\
 \left. \begin{matrix} \chi_x \\ \chi_y \\ \chi_s \end{matrix} \right\} \\
 \text{Curvatures}
 \end{matrix}$$



Laminate constitutive behavior (CLPT): the bad guys



$$\begin{Bmatrix} N_x \\ N_y \\ N_s \\ M_x \\ M_y \\ M_s \end{Bmatrix} = \begin{bmatrix} A_{11} & A_{12} & A_{16} & B_{11} & B_{12} & B_{16} \\ A_{12} & A_{22} & A_{26} & B_{12} & B_{22} & B_{26} \\ A_{16} & A_{26} & A_{66} & B_{16} & B_{26} & B_{66} \\ B_{11} & B_{12} & B_{16} & D_{11} & D_{12} & D_{16} \\ B_{12} & B_{22} & B_{26} & D_{12} & D_{22} & D_{26} \\ B_{16} & B_{26} & B_{66} & D_{16} & D_{26} & D_{66} \end{bmatrix} \begin{Bmatrix} \epsilon_x^0 \\ \epsilon_y^0 \\ \epsilon_s^0 \\ \chi_x \\ \chi_y \\ \chi_s \end{Bmatrix}$$



Desirable laminate elastic behaviors

Uncoupling $\mathbf{B} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

Membrane orthotropy $\mathbf{A} = \begin{bmatrix} A_{11} & A_{12} & 0 \\ A_{12} & A_{22} & 0 \\ 0 & 0 & A_{66} \end{bmatrix}$

Bending orthotropy $\mathbf{D} = \begin{bmatrix} D_{11} & D_{12} & 0 \\ D_{12} & D_{22} & 0 \\ 0 & 0 & D_{66} \end{bmatrix}$

Membrane isotropy $\mathbf{A} = \begin{bmatrix} A_{11} & A_{12} & 0 \\ A_{12} & A_{22} & 0 \\ 0 & 0 & \frac{A_{11} - A_{12}}{2} \end{bmatrix}$

Bending isotropy $\mathbf{D} = \begin{bmatrix} D_{11} & D_{12} & 0 \\ D_{12} & D_{22} & 0 \\ 0 & 0 & \frac{D_{11} - D_{12}}{2} \end{bmatrix}$

slido



Would you be able to design a laminate with ...

ⓘ Start presenting to display the poll results on this slide.



Would you be able to design a laminate with ...

Multiple Choice Poll 25 votes 25 participants

B=0 (uncoupled) - 19 votes



A orthotropic, B=0 - 15 votes



A isotropic (quasi-isotropic), B=0 - 18 votes



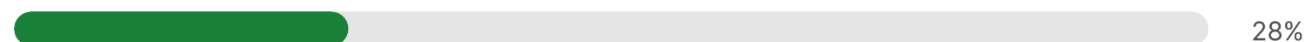
D orthotropic, B=0 - 7 votes



D isotropic, B=0 - 3 votes



A & D orthotropic, B=0 - 7 votes



A & D isotropic, B=0 - 2 votes



Desired properties...

... and ...

... design strategy

B = **0** (Uncoupled)

A orthotropic

A orthotropic, **B** = **0**

A isotropic (quasi-isotropic)

A isotropic, **B** = **0**

D orthotropic

D orthotropic, **B** = **0**

D isotropic

D isotropic, **B** = **0**

A & **D** orthotropic

A & **D** orthotropic, **B** = **0**

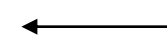
A & **D** isotropic

A & **D** isotropic, **B** = **0**

[60/0/-60],

[0/90/±45],

...



← Werren & Norris + symmetric

Symmetric

Balanced

Balanced + symmetric

Werren & Norris

Antisymmetric

?

?

?

Antisymmetric

?

?

?



Desired properties...

... and ...

... design strategy

$B = \mathbf{0}$ (Uncoupled)

A orthotropic

A orthotropic, $B = \mathbf{0}$

A isotropic (quasi-isotropic)

A isotropic, $B = \mathbf{0}$

D orthotropic

D orthotropic, $B = \mathbf{0}$

D isotropic

D isotropic, $B = \mathbf{0}$

A & D orthotropic

A & D orthotropic, $B = \mathbf{0}$

A & D isotropic

A & D isotropic, $B = \mathbf{0}$

Symmetric

Balanced

Balanced + symmetric

Werren & Norris

[60/0/-60],

[0/90/±45],

...



← Werren & Norris + symmetric

Antisymmetric

?

?

?

For uncoupling we are restricted to using symmetry

Antisymmetric

?

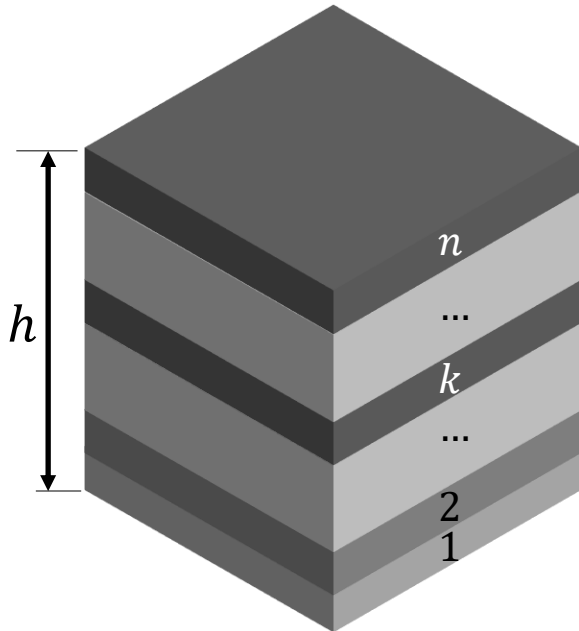
We do not have strategies to control the bending behavior

?

?



Stiffness matrices: their definition



$$\mathbf{A} = \frac{h}{n} \sum_{k=1}^n \mathbf{Q}(\delta_k)$$

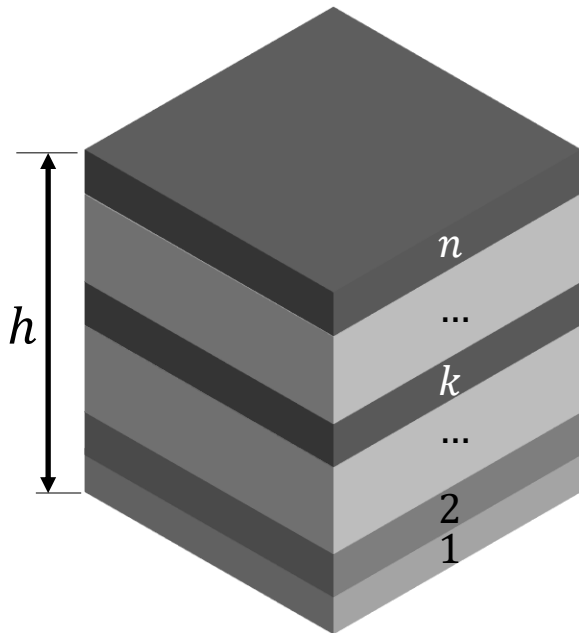
$$\mathbf{B} = \frac{1}{2} \frac{h^2}{n^2} \sum_{k=1}^n b_k \mathbf{Q}(\delta_k)$$

$$b_k = 2k - n - 1$$

$$\mathbf{D} = \frac{1}{12} \frac{h^3}{n^3} \sum_{k=1}^n d_k \mathbf{Q}(\delta_k)$$

$$d_k = 12k(k - n - 1) + 4 + 3n(n + 2)$$

Stiffness matrices: their definition



$$\mathbf{A} = \frac{h}{n} \sum_{k=1}^n \mathbf{Q}(\delta_k)$$

→ No dependence on ply positions k !

\mathbf{A} orthotropic Balanced

\mathbf{A} isotropic W&N layups

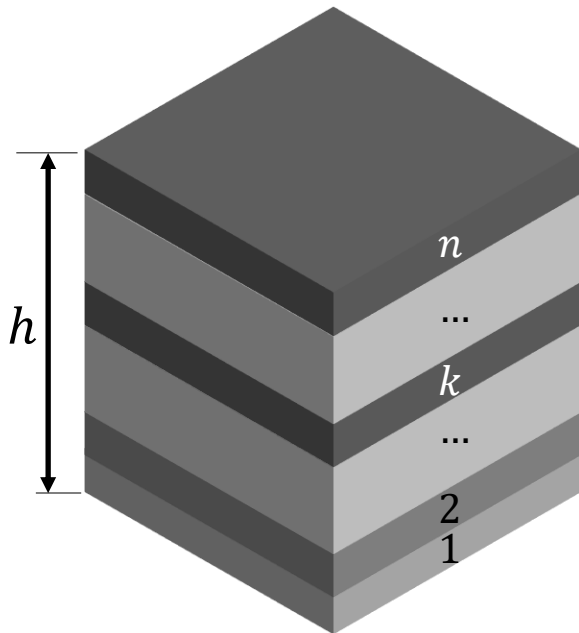
$$\mathbf{B} = \frac{1}{2} \frac{h^2}{n^2} \sum_{k=1}^n b_k \mathbf{Q}(\delta_k)$$

$$b_k = 2k - n - 1$$

$$\mathbf{D} = \frac{1}{12} \frac{h^3}{n^3} \sum_{k=1}^n d_k \mathbf{Q}(\delta_k)$$

$$d_k = 12k(k - n - 1) + 4 + 3n(n + 2)$$

Stiffness matrices: their definition



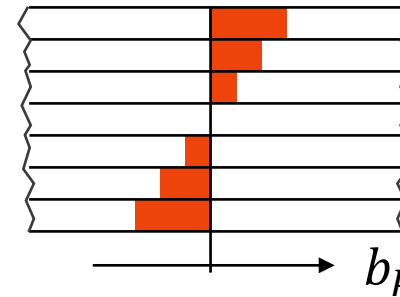
$$A = \frac{h}{n} \sum_{k=1}^n Q(\delta_k)$$

$$B = \frac{1}{2} \frac{h^2}{n^2} \sum_{k=1}^n b_k Q(\delta_k)$$

$$b_k = 2k - n - 1$$

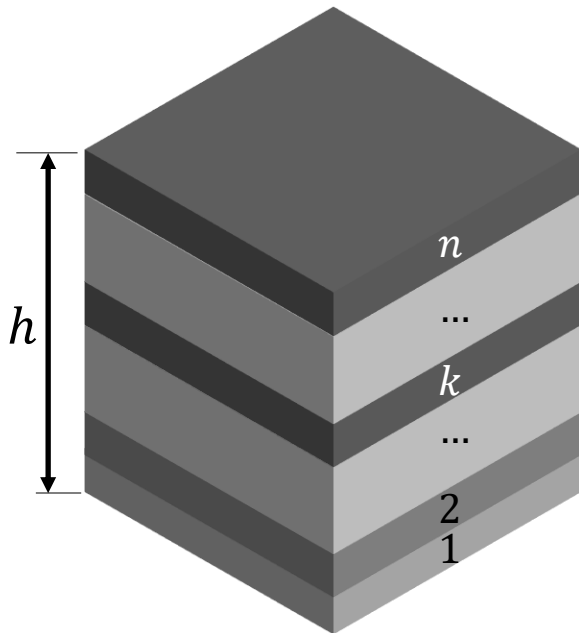
$$D = \frac{1}{12} \frac{h^3}{n^3} \sum_{k=1}^n d_k Q(\delta_k)$$

$$d_k = 12k(k - n - 1) + 4 + 3n(n + 2)$$



$B = 0$
 Symmetric

Stiffness matrices: their definition



$$A = \frac{h}{n} \sum_{k=1}^n Q(\delta_k)$$

$$B = \frac{1}{2} \frac{h^2}{n^2} \sum_{k=1}^n b_k Q(\delta_k)$$

$$b_k = 2k - n - 1$$

$$D = \frac{1}{12} \frac{h^3}{n^3} \sum_{k=1}^n d_k Q(\delta_k)$$

$$d_k = 12k(k - n - 1) + 4 + 3n(n + 2)$$

D orthotropic ----- Antisymmetric

D isotropic ?



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Quasi-trivial solutions

Uncoupled QT solutions: let's find them!

$$\mathbf{B} = \frac{1}{2} \frac{h^2}{n^2} \sum_{k=1}^n b_k \mathbf{Q}(\delta_k)$$

Orientations: $\vartheta_1, \vartheta_2, \dots, \vartheta_j, \dots, \vartheta_m$

$$G_j = \{k: \delta_k = \vartheta_j\}$$

$$\sum_{j=1}^m \sum_{k \in G_j} b_k \mathbf{Q}(\delta_k) \Rightarrow \sum_{j=1}^m \sum_{k \in G_j} b_k \mathbf{Q}(\vartheta_j)$$

$$\sum_{j=1}^m \mathbf{Q}(\vartheta_j) \sum_{k \in G_j} b_k$$

$$\sum_{k \in G_j} b_k = 0 \quad \forall j = 1, \dots, m \quad \Rightarrow \mathbf{B} = \mathbf{0}$$

QT uncoupled solutions!

Sample laminate: $[\vartheta_1/\vartheta_2/\vartheta_2/\vartheta_3/\vartheta_1/\vartheta_1/\vartheta_2]$

Orientations: $\vartheta_1, \vartheta_2, \vartheta_3$

$$G_1 = \{1, 5, 6\}$$

$$G_2 = \{2, 3, 7\}$$

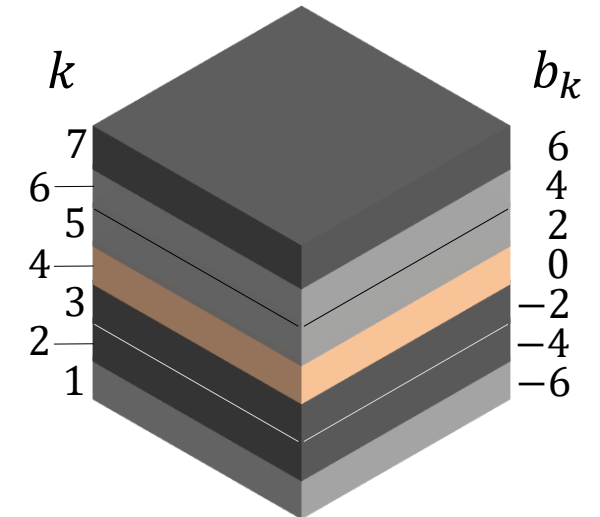
$$G_3 = \{4\}$$

$$j = 1 \Rightarrow -6 + 2 + 4 = 0$$

$$j = 2 \Rightarrow -4 - 2 + 6 = 0$$

$$j = 3 \Rightarrow 0$$

$$\Rightarrow \mathbf{B} = \mathbf{0}$$



Extension-bending-homogeneous and quasi-homogeneous QT solutions

$$\mathbf{A} = \frac{h}{n} \sum_{k=1}^n \mathbf{Q}(\delta_k)$$

$$\mathbf{A}^* = \frac{\mathbf{A}}{h}$$

$$\mathbf{B} = \frac{1}{2} \frac{h^2}{n^2} \sum_{k=1}^n b_k \mathbf{Q}(\delta_k)$$

$$\mathbf{D} = \frac{1}{12} \frac{h^3}{n^3} \sum_{k=1}^n d_k \mathbf{Q}(\delta_k)$$

$$\mathbf{D}^* = 12 \frac{\mathbf{D}}{h^3}$$

$$\mathbf{C} = \mathbf{A}^* - \mathbf{D}^* = \frac{1}{n^3} \sum_{k=1}^n c_k \mathbf{Q}(\delta_k)$$

$$c_k = n^2 - d_k$$

$$\sum_{k \in G_j} c_k = 0 \quad \forall j = 1, \dots, m \quad \Rightarrow \mathbf{C} = \mathbf{0}$$

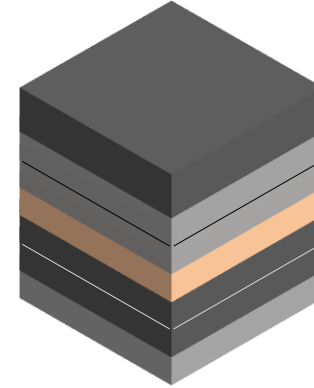
QT extension-bending homogeneous solutions!

$$\left\{ \begin{array}{l} \sum_{k \in G_j} b_k = 0 \quad \forall j = 1, \dots, m \quad \Rightarrow \mathbf{B} = \mathbf{0} \\ \sum_{k \in G_j} c_k = 0 \quad \forall j = 1, \dots, m \quad \Rightarrow \mathbf{C} = \mathbf{0} \end{array} \right.$$

QT quasi-homogeneous solutions!

QT solutions: a few remarks

- No dependence on $\mathbf{Q}(\delta_k)$:
 - $\sum_{k \in G_j} b_k = 0 \quad \forall j = 1, \dots, m \Rightarrow \mathbf{B} = \mathbf{0}$
 - $\sum_{k \in G_j} c_k = 0 \quad \forall j = 1, \dots, m \Rightarrow \mathbf{C} = \mathbf{0}$
 \Rightarrow orientations can be chosen freely
- $\mathbf{C} = \mathbf{0} \Rightarrow \mathbf{A}^* = \mathbf{D}^*$
 \Rightarrow bending behavior can be designed by together with extension one!
- Symmetric layups are a (small!) sub-class of uncoupled QT solutions



n	N. of groups m															Total
	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
7	0	1	<u>1</u>	0	0	0	0	0	0	0	0	0	0	0	2	
8	1	0	<u>1</u>	0	0	0	0	0	0	0	0	0	0	0	2	
9	0	1	2	<u>1</u>	0	0	0	0	0	0	0	0	0	0	4	
10	0	4	0	<u>1</u>	0	0	0	0	0	0	0	0	0	0	5	
11	0	0	9	4	<u>1</u>	0	0	0	0	0	0	0	0	0	14	
12	1	8	9	0	<u>1</u>	0	0	0	0	0	0	0	0	0	19	
13	0	0	25	32	6	<u>1</u>	0	0	0	0	0	0	0	0	64	
14	0	37	34	17	0	<u>1</u>	0	0	0	0	0	0	0	0	89	
15	0	0	10	207	78	9	<u>1</u>	0	0	0	0	0	0	0	305	
16	0	58	305	96	29	0	<u>1</u>	0	0	0	0	0	0	0	489	
17	0	0	2	893	895	144	12	<u>1</u>	0	0	0	0	0	0	1947	
18	0	114	1492	1262	208	45	0	<u>1</u>	0	0	0	0	0	0	3122	
19	0	0	0	2216	8192	2663	264	16	<u>1</u>	0	0	0	0	0	13352	
20	0	0	7391	11240	3683	396	66	0	<u>1</u>	0	0	0	0	0	22777	
21	0	0	0	4936	59701	39986	6283	406	20	<u>1</u>	0	0	0	0	111333	
22	0	0	29144	101207	49008	8869	694	93	0	<u>1</u>	0	0	0	0	189016	
23	0	0	0	6369	346057	519231	141298	13130	626	25	<u>1</u>	0	0	0	1026737	
24	0	0	75421	844224	665507	156300	18569	1118	126	0	<u>1</u>	0	0	0	1761266	
25	0	0	0	3863	1775560	6116700	2797033	388970	24060	893	30	<u>1</u>	0	0	11107110	
26	0	0	96098	6277657	8836070	2900569	410040	35272	1708	166	0	<u>1</u>	0	0	18557581	
27	0	0	0	660	6978620	61170759	51236513	10978670	941503	41907	1261	36	<u>1</u>	0	131349930	
28	0	0	136700	40159296	112753933	54164504	9788692	940584	62404	2520	214	0	<u>1</u>	0	218008848	
29	0	0	0	20	21692599	561464759	868233466	285533218	34157728	1974630	66910	1682	42	<u>1</u>	1773125055	

Table 4.1: Number of independent QT uncoupled solutions obtained as a function of the total number of plies, n , and of the number of saturated orientation groups, m . (— Symmetric solutions)

Desired properties...

... vs ...

...design strategy

$\mathbf{B} = \mathbf{0}$ (Uncoupled)

\mathbf{A} orthotropic

\mathbf{A} orthotropic, $\mathbf{B} = \mathbf{0}$

\mathbf{A} isotropic (quasi-isotropic)

\mathbf{A} isotropic, $\mathbf{B} = \mathbf{0}$

\mathbf{D} orthotropic

\mathbf{D} orthotropic, $\mathbf{B} = \mathbf{0}$

\mathbf{D} isotropic

\mathbf{D} isotropic, $\mathbf{B} = \mathbf{0}$

\mathbf{A} & \mathbf{D} orthotropic

\mathbf{A} & \mathbf{D} orthotropic, $\mathbf{B} = \mathbf{0}$

\mathbf{A} & \mathbf{D} isotropic

\mathbf{A} & \mathbf{D} isotropic, $\mathbf{B} = \mathbf{0}$

QT ($\mathbf{B} = \mathbf{0}$)

Balanced

Balanced + QT ($\mathbf{B} = \mathbf{0}$)

Werren & Norris

Werren & Norris + QT ($\mathbf{B} = \mathbf{0}$)

Antisymmetric / balanced + QT ($\mathbf{C} = \mathbf{0}$)

Balanced + QT ($\mathbf{B} = \mathbf{0}$, $\mathbf{C} = \mathbf{0}$)

Werren & Norris + QT ($\mathbf{C} = \mathbf{0}$)

Werren & Norris + QT ($\mathbf{B} = \mathbf{0}$, $\mathbf{C} = \mathbf{0}$)

Antisymmetric / Balanced + QT ($\mathbf{C} = \mathbf{0}$)

Balanced + QT ($\mathbf{B} = \mathbf{0}$, $\mathbf{C} = \mathbf{0}$)

Werren & Norris + QT ($\mathbf{C} = \mathbf{0}$)

Werren & Norris + QT ($\mathbf{B} = \mathbf{0}$, $\mathbf{C} = \mathbf{0}$)



Desired properties...

... VS ...

...design strategy

$B = 0$ (Uncoupled)

A orthotropic

A orthotropic, $B = 0$

A isotropic (quasi-isotropic)

A isotropic, $B = 0$

D orthotropic

D orthotropic, $B = 0$

D isotropic

D isotropic, $B = 0$

A & D orthotropic

A & D orthotropic, $B = 0$

A & D isotropic

A & D isotropic, $B = 0$

QT ($B = 0$)

Balanced

Balanced + QT ($B = 0$)

Werren & Norris

Werren & Norris + QT ($B = 0$)

Antisymmetric / balanced + QT ($C = 0$)

Balanced + QT ($B = 0, C = 0$)

Werren & Norris + QT ($C = 0$)

Werren & Norris + QT ($B = 0, C = 0$)

Antisymmetric / Balanced + QT ($C = 0$)

Balanced + QT ($B = 0, C = 0$)

Werren & Norris + QT ($C = 0$)

Werren & Norris + QT ($B = 0, C = 0$)

Much wider design space for all situations where uncoupling is required

Design strategies for bending behavior become trivial with QT with $C=0$



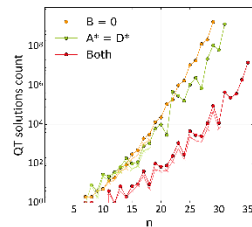
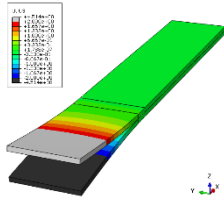
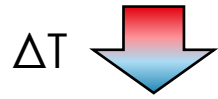


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Concluding remarks

Concluding remarks



- A few things that were not mentioned:
 - Thermo-hygro-elasticity
 - More subtle properties
 - Less relevant to laminates design

- Successful applications:
 - Fully-Uncoupled Multi-Directional delamination specimens
 - Optimisation problems
 - Design of VAT laminates

- Limitations to adoption:
 - Limited availability
 - Complex search algorithm required
 - Computational power limitations



Funded by the European Union

Any dissemination of results/communication activity related to the project reflects only the author's view.



*Thank you
for your attention!*



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Part of:

